

What is the analog of the theorem that x, z determine a curve?
 Do H, K determine a surface? F is constant? Curves
 $3-2=1$ $3-1=2$
 map \uparrow require $\text{rel'n between } H \text{ \& } K?$

Difference — canonical coords

Instead, for the simplest analog, ask what determines a parametrized surface / isom.
 curves $\rightarrow K, z$, speed vector

Idea — get isom (\mathbb{R}^3) -isom using a Frame (cf. M-C)

$$\text{Frame } F = [\psi_1, \psi_2, N]$$

Q: can you always choose ψ so F is orthonormal?

A: probably not \rightarrow not locally isometric (why?)

$F^{-1} dF$ matrix of 1-forms do we recognize any?

Think $B_{ij}^1 = h_{ij}$

Relat: $\Gamma_{ij}^k = \Gamma_{ji}^k$

$$\Gamma_{ij}^k = \Gamma_{ji}^k \psi_{ik} + h_{ij} N_j$$

↳ this is the Du

$$dF = F \begin{bmatrix} \Gamma_{11}^1 & \Gamma_{21}^1 & -B_{11}^1 \\ \Gamma_{11}^2 & \Gamma_{21}^2 & -B_{11}^2 \\ h_{11} & h_{21} & 0 \end{bmatrix} dx^i$$

Can you solve this for F ? Only if X_1, X_2 commute on $\mathbb{R}^2 \times G$

$$F^{-1} dF = A \Rightarrow \boxed{dA - A \wedge A = 0} \leftarrow \text{write out}$$

Converse: F^i_j as a function on G

vector field
 X_i defined by

$$\mathcal{D}_i F^i_j = F^i_k A^k_{i,j}$$

$$\mathcal{D}_i = F^i_k A^k_{i,j} \frac{\partial}{\partial F^i_j} + \frac{\partial}{\partial x^i}$$

A just depends on X .

$$[\mathcal{D}_i, \mathcal{D}_j] F^i_k = \mathcal{D}_i (F^i_l A^l_{j,k})$$

$$= F^i_l A^l_{j,k} A^k_{i,j} + F^i_k$$

Miracle 2

Γ determined by Riemann metric = its first derivatives

- $\frac{1}{2} \langle \psi_1, \psi_1 \rangle_1 = \langle \psi_{11}, \psi_{11} \rangle \rightarrow \text{recover } \psi_{11}^{\text{tan}}$
- $\langle \psi_1, \psi_2 \rangle_1 = \langle \psi_{11}, \psi_{21} \rangle + \langle \psi_{12}, \psi_{22} \rangle$
 $\frac{1}{2} \langle \psi_1, \psi_2 \rangle_2$
- $\frac{1}{2} \langle \psi_1, \psi_1 \rangle_2 = \langle \psi_{12}, \psi_{12} \rangle \rightarrow \text{recover } \psi_{12}^{\text{tan}}$
- $\frac{1}{2} \langle \psi_2, \psi_2 \rangle_1 = \langle \psi_{12}, \psi_{22} \rangle$

Thm (Bonnet) Suppose (E, F, G, e, f, g)

given on $V \subseteq \mathbb{R}^3$, with $\left\{ \begin{array}{l} EG - E^2 > 0 \\ G > 0 \end{array} \right\}$,

satisfying Gauss + Codazzi. Then $\forall p \in V$,

\exists neighborhood U of p and $X: U \rightarrow \mathbb{R}^3$ s.t.

$X(U)$ has coefficients of 1st & 2nd order given by (E, F, G, e, f, g) . Any 2 differ by rigid motion.

Defn A connection in E is a map

$$\nabla: \text{Vect}(M) \times C^\infty(E) \rightarrow C^\infty(E)$$

that is

(i) linear over $C^\infty(M)$ in X

(ii) a derivation over $C^\infty(M)$ in e

i.e. \mathbb{R} -linear in both and

$$(i) \nabla_{fX} e = f \nabla_X e$$

$$(ii) \nabla_X fe = (Xf)e + f \nabla_X e$$

Props As we've seen w/ v's, ℓ , etc.

$(\nabla_X e)_p$ depends only on X_p , e in a neighborhood of p .

~~Difference~~ w/ Lie bracket - torsion in X !

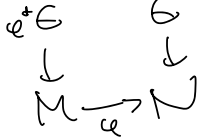
Now we'll build up to seeing why ∇ describes a connection.

Ex On $E = T\mathbb{R}^n$,

$$\nabla_x Y = X(Y^i) \frac{\partial}{\partial y^i}$$

is the Euclidean connection (check)

Ex Pull-back connection:



Recall sections of e^*E are locally

$$\sum F^a(e_a \circ e)$$

$$(e^*\nabla)_x F^a(e_a \circ e) = X(F^a)(e_a \circ e) + F^a(\nabla_{\text{lex}} e_a) \circ e$$

eg $\alpha: \mathbb{I} \rightarrow \mathbb{R}^3$ curve.

$$\alpha' = \frac{D\alpha}{dt} = \sum F^i(t) \frac{\partial}{\partial x^i} \text{ section of } \pi^* T\mathbb{R}^3$$

$$(e^*\nabla)_{\frac{\partial}{\partial t}} \alpha' = \left(\frac{\partial F^i}{\partial t} \right) \frac{\partial}{\partial x^i} + 0 = \alpha''.$$

Main ex: $(F \subset S \rightarrow \mathbb{R}^n)$ is α_x subfld, and (isometric immersion)

$$\pi: \pi^* \mathbb{R}^n \rightarrow TS$$

is the orthogonal projection

$$\text{then } \nabla_x Y := \pi(i^* \nabla_x Y)$$

is a connection on TS

More generally, if $F \subseteq (E, \nabla)$ is any sub-bundle, π any proj,

$$\nabla_x F = \pi(\nabla_x^E F).$$

T
Prove }
J

Connection coefficients (Christoffel symbols)

If E_α basis for E , $\frac{\partial}{\partial x^i}$ a coord basis for TM , then

$$\nabla_i E_\alpha = \nabla_{\frac{\partial}{\partial x^i}} E_\alpha = E_\beta \Gamma_{i\alpha}^\beta$$

eg take $E = TM$, $E_\alpha = E_i$

Warning - not a tensor eg,

$$\nabla_i (E_\alpha g^\alpha_\beta) = (\nabla_i E_\alpha) g^\alpha_\beta + E_\alpha g^\alpha_\beta (\nabla_i g^\alpha_\beta) + \nabla_i g^\alpha_\beta$$

$$\nabla_i \tilde{E}_\alpha = E_\beta \Gamma_{i\alpha}^\beta + \tilde{E}_\alpha$$

$$\tilde{\Gamma} = g^i \nabla g + \tilde{g} \nabla g$$

Rule Comm on tensor bundles,
total covariant derivative
Difference of connections

Next time Module 2 in general.